HCMC UNIVERSITY OF TECHNOLOGY AND EDUCATION AUTOMATION AND CONTROL ENGINEERING

TECHNOLOGY

Faculty of Electrical and Electronic Engineering **Department of Automatic Control**

Undergraduate Program

SYLLABUS

- 1. Course name: ELECTRICAL EQUIPMENT and PNEUMATIC
- 2. Course code: EEPN320746
- **3.** Credits: 2 (2/0/4)

Duration: 15 weeks (30h main course and 60h self-study)

4. Instructors:

- 1- Assoc. Prof. PhD. Le Chi Kien
- 2- M.Eng. Nguyen Tan Doi
- 3- M.Eng. Ta Van Phuong

5. Course conditions

Prerequisites: Power Electronics, Electric Machines Corequisites: N/A

6. Course description

The course provides students the knowlegde of electrical equipments, pneumatics, inverters, servo motors. Students know how to design a hardwired system, including power and control circuits, electrical pneumatic circuits. And students can set parameters of inverters, servo motors to control a automatic system.

7. Course Goals

Goals	Goal description (This course provides students:)	
G1	An ability to understand components and operation of electrical and pneumatic circuits	1.1, 1.2
G2	An ability to read and understand English document	2.1, 3.2
G3	An ability to analyse and design power and control circuits for a system	2.2, 4.4

* Note: High: H; Medium: M; Low: L

8. Course Learning Outcomes (CLOs)

CLOs		Description (After completing this course, students can:)	
G1	G1.1	Represent the structures and specifications of electrical and pneumatic devices	1.1, 1.2
	G1.2	Select electrical and pneumatic devices for a hardwired system	1.1, 1.2
G2	G2.1	Read English user manual of devices	2.1, 3.2
G3	G3.1	Design a power and control circuit for a system	2.2, 4.4
	G3.2	Diagnose and troubleshoot an inverter, servo motor system	2.2

9. Study materials

- Textbooks:

[1] He thong dieu khien tu dong khi nen, Nguyen Ngoc Phuong, Nguyen Truong Thinh, NXB Khoa hoc và Ky thuat, 2012

[2] Industrial servo control systems: fundamentals and applications, George W. Younkin, 2nd Edition, New York: Marcel Dekker, 2003

- References:

[1] Hydraulics and Pneumatics: A Technician's and Engineer's Guide, Andrew Parr, 3rd Edition Butterworth-Heinemann, 2011

[2] Servo Motors and Industrial Control Theory, Riazollah Firoozian, Springer, 2009 Edition, 2008

10. Sudent Assessments

- Grading points: 10

- Planning for students assessment is followed:

Туре	Contents	Linetime	Assessment techniques	ELOs	Rate (%)
Midterms					50
Exercise 1	- Select devices - Design electrical circuits	Week 5	Writing	G1.1, G1.2	20
Exercise 2	- Select devices - Design pneumatic circuits	Week 10	Writing	G1.3, G1.4	20
Exercise 3	 Select devices Design electrical and pneumatic circuits Inverter and servo motors system 	Week 12	Online	G1.1,G1.2 G3.1,G3.2	10
Final Exam					50
Final Exam	 Design electrical and pneumatic circuits Design inverter, servo motor system 		Writing	G2.1, G2.2	50

11. Course details:

Weeks	Contents	ELOs
	Chapter 1: <hardwired system=""> (10/0/20)</hardwired>	
	A/ Contents and teaching methods: (10)	G1.1
	Contents:	G1.2
	1.1 Structure, Operation of electrical equipments	G2.1
10245	1.2 Power circuits	G3.1
1,2,3,4,5	1.3 Control circuits	
	1.4 Design hardwired system	

	Teaching methods:	
	- Presentation.	
	- Video clips	
	- Manual guide	
	- Simulation	
	- Group discussion.	
	<i>B</i> /Self-study contents: (20)	
	- Using simulation software CADe	
	- Draw and simulate the circuits	
	- Read user manual	
	Chapter 2: <electrical and="" circuits="" pneumatic=""> (10/0/20)</electrical>	
	A/ Contents and teaching methods: (10)	G1.1
	Contents:	G1.2
	2.1 Pneumatic system	G2.1
	2.2 Components of a pneumatic system	G3.1
	2.3 Structure and Operation of a pneumatic system	
	2.4 Electrical and pneumatic system	
	2.5 Design an electrical and pneumatic system	
6,7,8,9,10	Teaching methods:	
	- Presentation.	
	- Video clips	
	- Manual guide	
	- Simulation	
	- Group discussion.	
	<i>B</i> /Self-study contents: (20)	
	- Using simulation software CADe, FluidSIM	
	- Draw and simulate the circuits	
	- Read user manual	
	Chapter 3: <inverter and="" applications=""> (6/0/12)</inverter>	
	A/ Contents and teaching methods:(6)	G2.1
	Contents:	G3.1
	3.1 Structure and Operation of Inverter	G3.2
	3.2 Power circuit	05.2
	3.3 Control circuit	
	3.4 Setting parameters	
11,12,13	3.5 Control inverter by External terminals and BOP	
	3.6 Diagnose and Troubleshooting	
	3.7 Applicaions	
	Teaching methods:	
	- Presentation.	
	- Video clips	
	- Manual guide	
	- Group discussion.	

	<i>B</i> /Self-study contents: (12)	
	- Read user manual of inverter: Siemens, Mitsubishi, Allen Bradley	
	- Design a system using inverter and PLC	
	Chapter 4: <servo system=""> (4/0/8)</servo>	
	A/ Contents and teaching methods: (4)	G2.1
	Contents:	G3.1
	4.1 Introduction to servo system	
	4.2 Components of a servo system	G3.2
	4.3 Wiring Power circuit	
	4.4 Wiring Control circuit	
	4.5 Setting parameters of servo driver	
	4.6 Diagnose and Troubleshooting	
14,15	4.7 Servo driver and PLC	
	Teaching methods:	
	- Presentation.	
	- Video clips	
	- Manual guide	
	- Group discussion.	
	<i>B</i> /Self- study contents: (8)	
	- Read user manual of servo motor: Siemens, Mitsubishi, Omron	
	- Design a system using servo motor and PLC	

12. Learning ethics:

Home assignments and projects must be done by the students themselves. Plagiarism found in the assessments will get zero point

13. First approved date: August 01 2017

14. Approval level:

Dean	Department	Instructor	
Assoc. Prof. PhD.	Assoc. Prof. PhD. Truong	Assoc. Prof. PhD. Le Chi	
Nguyen Minh Tam	Dinh Nhon	Kien	

15. Syllabus updated process

1 st time: Updated content dated	Instructors
2 st time: Updated content dated	Head of department